

A hybrid *level-set/embedded boundary* numerical method for the simulation of solidification/melt problems

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Introduction

Numerical method

The *level-set* method

Embedded boundaries

Hybrid Embedded boundaries/
level-set method

Test cases

1D solidification

Melt of a particle

Solidification/melt problems



Figure: Ice falling from bridge cables



Figure: Power outage due to ice



Figure: Drone de-icing of a wind turbine



Figure: Iced wing

Solidification/melt problems



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How can we properly do numerical simulation of solidification/melt problems ?

- ϕ a higher-dimensional function
- Interface Γ : zero level-set of ϕ (hypersurface)¹.

In our cases, ϕ is initialized as a signed distance function.

Level set method

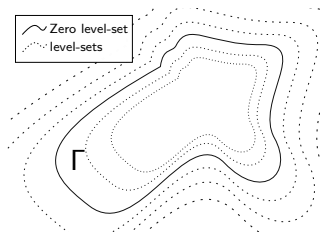


Figure: Interface Γ and different level-sets of ϕ

¹S. Osher and J. A. Sethian. "Fronts propagating with curvature-dependent speed: algorithms based on Hamilton-Jacobi formulations". In: *Journal of computational physics* 79.1 (1988), pp. 12–49.

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In our cases, ϕ is initialized as a signed distance function.

$$\partial_t \phi + \mathbf{v}_{\text{pc}} \cdot \nabla \phi = 0. \quad (1)$$

\mathbf{v}_{pc} : phase change velocity field.

Level set method

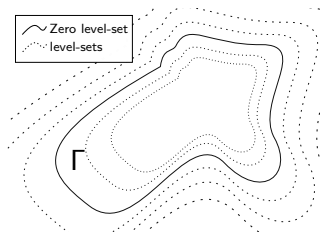


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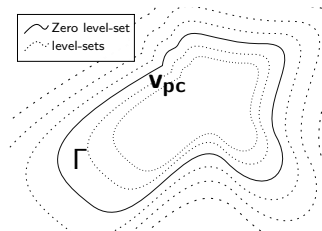


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\mathbf{v}_{pc} : phase change velocity field.

⇒ Construct a continuous \mathbf{v}_{pc} field using $\mathbf{v}_{\text{pc}}|_{\Gamma}$ and ϕ

Level set method

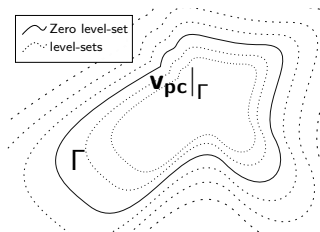


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Reconstruction of the velocity

- Extrapolation² of $\mathbf{v}_{pc}|_{\Gamma}$ in the vicinity of the interface:

$$\frac{\partial v_{pc}}{\partial t} + \text{sign}(\phi) (\mathbf{n} \cdot \nabla v_{pc}) = 0$$

with:

$$\mathbf{n} = \frac{\nabla \phi}{|\nabla \phi|}$$

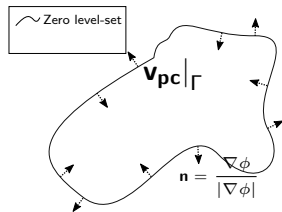


Figure: Local advection of \mathbf{v}_{pc}

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⇒ Narrow band approximation.

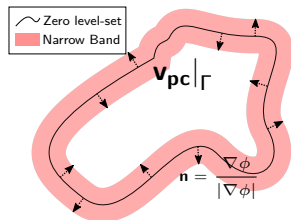


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Issue

- Advection \rightarrow numerical diffusion

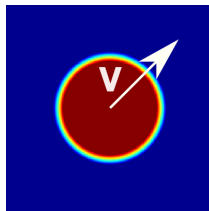
\Rightarrow correction method is required

\Rightarrow reinitialization/redistancing of ϕ^0 :

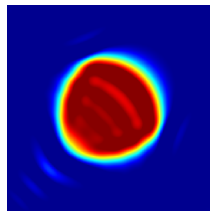
$$\frac{\partial \phi}{\partial t} = \text{sgn}(\phi^0) (1 - |\nabla \phi|)$$

Solved only in the Narrow Band³

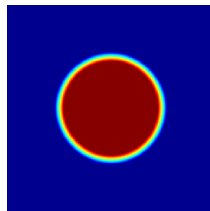
Redistancing of ϕ



(a) Initial ϕ field



(b) Final ϕ w/o redistancing



(c) Final ϕ w/ redistancing

Figure: Redistancing required

³Giovanni Russo and Peter Smereka. "A remark on computing distance functions". In: *Journal of Computational Physics* 163.1 (2000), pp. 51–67.

Level-set methods

Pros

- Simple to implement
- Made for flows with complex interfacial topologies; splitting/merging, shear...

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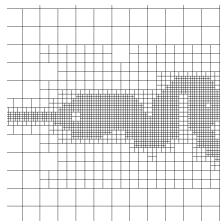
Cons

- Non-conservative (reinitialization step)

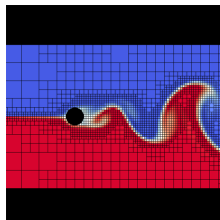
Concept

- Intersect a boundary of general shape with a grid (here Cartesian)
- Modify volume and area fractions of the intersected cells (Finite Volume formulation)

Embedded Boundaries



(a) Grid



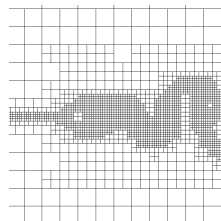
(b) Passive tracer with an
cylindrical embedded boundary

Figure: Flow past a circle with embedded boundaries

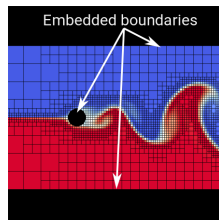
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Embedded Boundaries

Gradients on the interface

Johansen and Colella's method⁴:

$$\nabla\phi|_f = \frac{1}{d_2 - d_1} \left(\frac{d_2}{d_1}(\phi_f - \phi_1) - \frac{d_1}{d_2}(\phi_f - \phi_2) \right)$$

second-order accurate

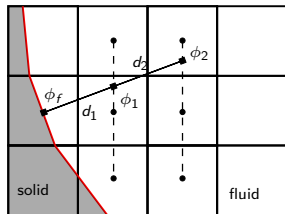


Figure: embedded boundary principle

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**Non-moving boundaries, or solid movement using
ALE formulation in its original formulation !**

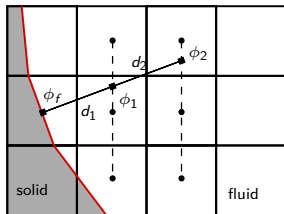


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Hybrid Embedded boundaries/*level-set* method

Remark

- Level-set function used for definition of the embedded boundaries

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⇒ Combine a *level-set* method with embedded boundaries

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Main idea

- 2 fluids : Calculation inside and outside of the boundary with two set of fields
- v_{pc} only field defined in both phases with a meaning

We use the gradients defined by the high-order approximation of the embedded boundary method and set:

$$\text{Stefan condition:} \quad \mathbf{v}_{pc}|_{\Gamma} = \frac{1}{L_H} \left(\frac{\lambda_L}{\rho_L} \nabla T_L|_{\Gamma} - \frac{\lambda_S}{\rho_S} \nabla T_S|_{\Gamma} \right)$$

$$\text{Gibbs-Thomson equation:} \quad T_{\Gamma} = T_m - \epsilon_{\kappa} * \kappa - \epsilon_v * v_{pc}$$

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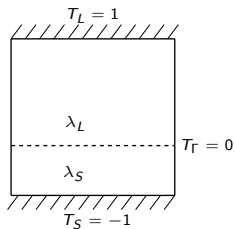
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- Possible use of 2 different solvers

1D solidification - diffusion



(a) Schematic of the case

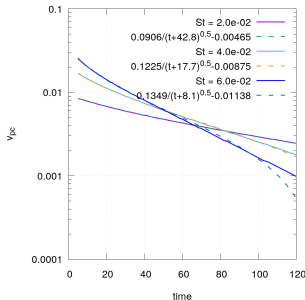
(b) $v_{pc}|_{\Gamma}$ for 3 different St

Figure: 1D solidification case

Initial position off equilibrium

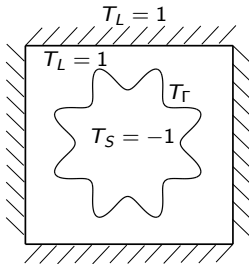
In both phases: $\frac{\partial T}{\partial t} = D \Delta T$

$$v_{pc}|_{\Gamma} \approx A \times t^{-0.5}$$

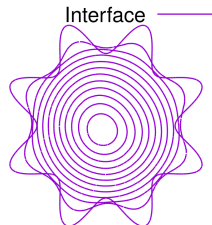
$$\lambda_L = \lambda_S = 1 ; D = 1 ; St = \frac{C_p \Delta T}{L_H}$$

2D star-shaped ice particle melting

- Interface $\Gamma(r, \theta): r(1 + 0.2 * \cos(8\theta)) - 1 = 0$
- Gibbs-Thomson: $T_{\Gamma} = T_m - \epsilon_{\kappa} * \kappa - \epsilon_v * v_{pc}$



(a) test

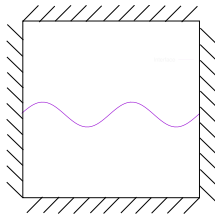


(b) Interface at different times during calculation

Figure: 2D star-shaped ice particle

Perspectives

- In-depth analysis of simple cases (linear stability)
- Dendrite growth
- Solidification with convection



Code available at : <http://basilisk.fr/sandbox/alimare/>

Thank you for your attention

Stencil for interpolation can be too small, leading to a decrease in the order of accuracy of the method.
⇒ Can be circumvented by using Adaptive Mesh Refinement.

Known Issue

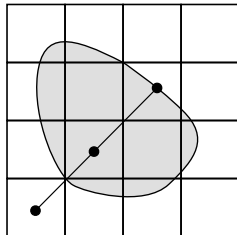


Figure: Embedded zone is too small for interpolation

Same case with an initial Gaussian interface
Case with both melting and solidification
due to the Gibbs-Thomson relation.
Temperature field

Gaussian bump

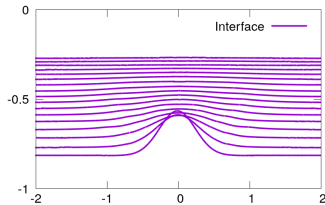
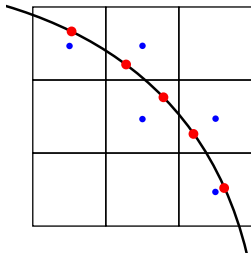


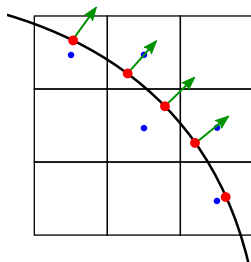
Figure: Interface at different times during the simulation

Hybrid Embedded boundaries/*level-set* method



(a)

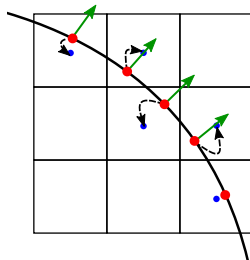
Figure: Initial condition for the v_{PC} reconstruction

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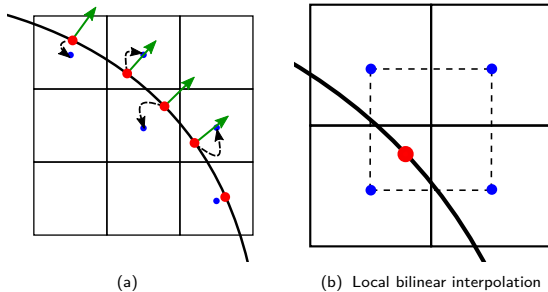


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